

MODERN SENSOR NETWORKS

Industrial communication **protocols** in brief



ÓBUDAI EGYETEM
ÓBUDA UNIVERSITY

BALLUFF

 *innovating automation*

Emil Mógor
development engineer
PD-NMO, Balluff-Elektronika Kft





ÓBUDAI EGYETEM
ÓBUDA UNIVERSITY

BALLUFF

B *innovating automation*

Zoltán Kása
Head of PD-NMO,
Balluff-Elektronika Kft



Comprehensive **portfolio** of sensor, identification and image processing solutions including network technology and software



More than **30000** customers and partners worldwide



On site in over 60 countries: with own subsidiaries and numerous representatives **37**

AT A **GLANCE**

More than **100** years Balluff: since 1921



experienced manufacturer with **6** production sites worldwide

4. generation family-owned company



504 million EUR in group sales 2021



about **3600** employees worldwide

1921: THE BALLUFF STORY BEGAN

Automate, innovate, celebrate!
One century of Balluff

1921 Gebhard Balluff founds the company as a mechanical repair workshop

1956 Entry into sensor technology and further development of the portfolio

1971 Founding of the first foreign subsidiary and start of internationalization

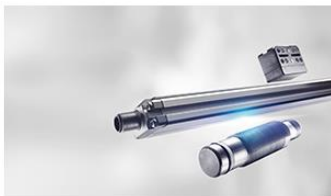
2021 Continuous development of automation innovations to meet customer needs

AT A

GLANCE

100 Years of Balluff:
since 1921

OUR PORTFOLIO



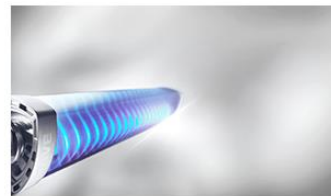
Sensors



Industrial Networking



RFID



Human Machine Interfaces



Machine Vision
and Optical Identification



Power Supplies



Connectivity



Accessories



Software



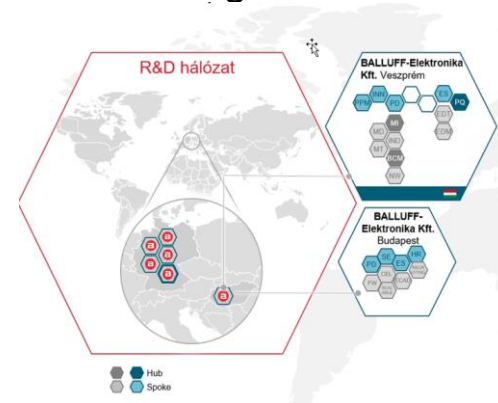
System solutions

... SINCE 33 YEARS IN VESZPRÉM



We are

The largest production site
Second largest R&D site



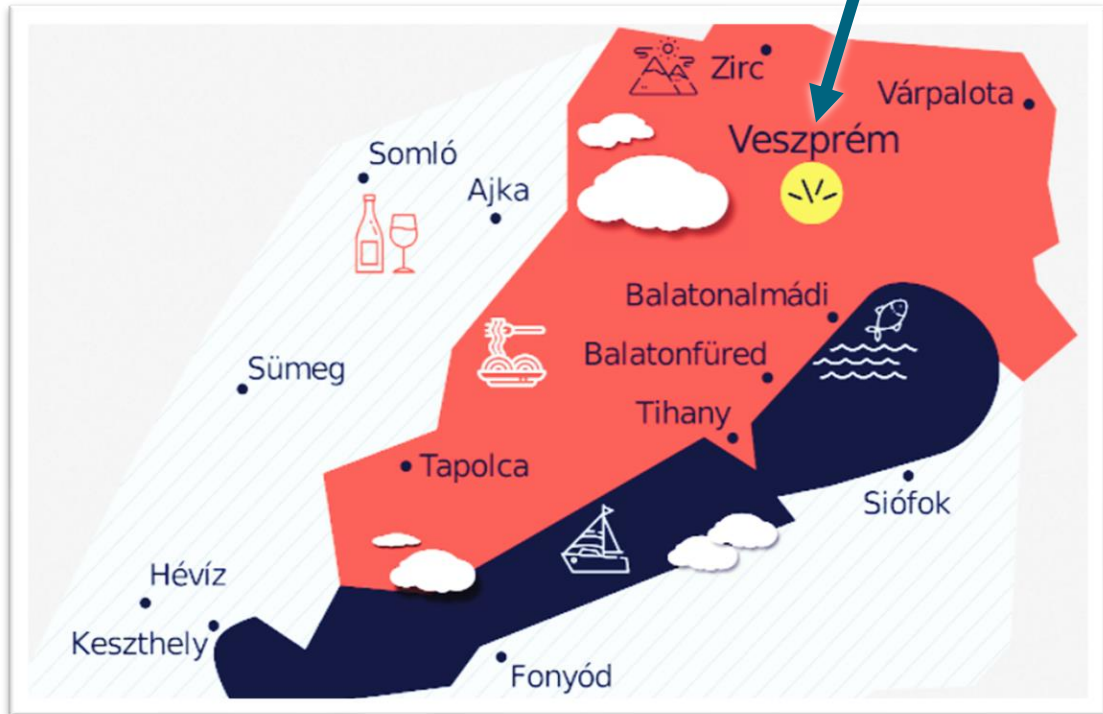
Development office in
Budapest since 2022

WHERE IS VESZPRÉM?



Veszprém-Balaton 2023
European Capital of Culture

Visit us in 2023



SENSOR NETWORKS - INTRO

Control theory – Basic terms

Sensor: is a device which detects or measures a physical property and records, indicates, or otherwise responds to it.

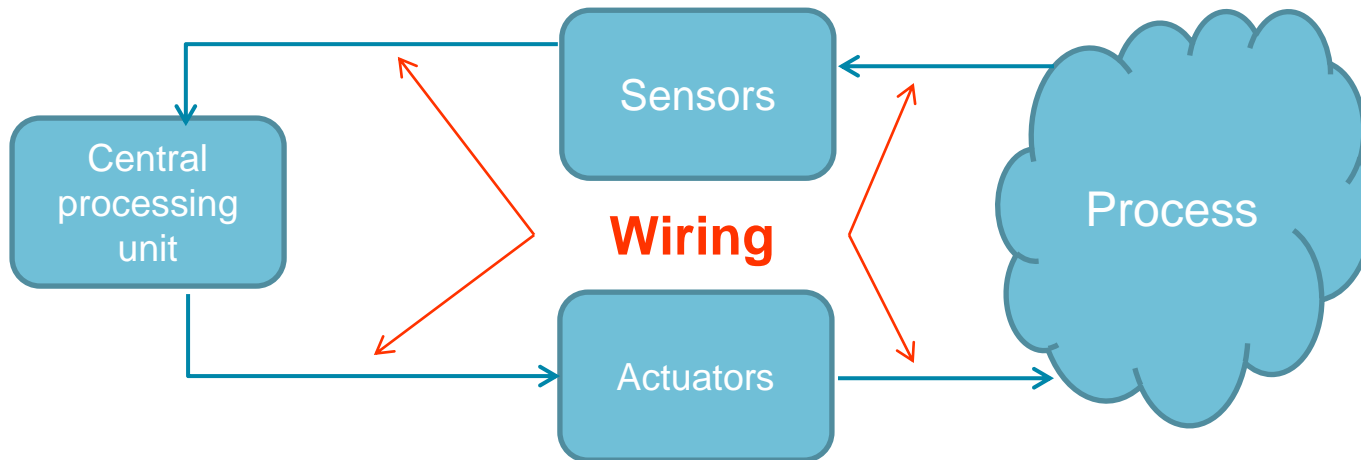
Actuator: An actuator is a device that moves or controls some mechanism. An actuator turns a control signal into mechanical action such as an electric motor..

Control: an operation that intervenes in a technical process in order to start, maintain, ensure its course according to plan, change or stop it.



SENSOR NETWORKS - INTRO

Control loop

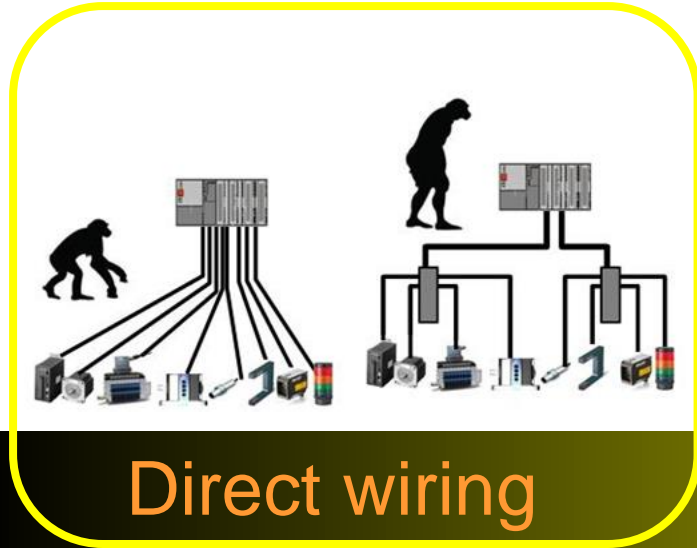


Become important if:

- The system contains numerous sensors and actuators
- Distance between control unit and process is large
- Harsh environment of the process (temperature, pressure, liquids etc.)

SENSOR NETWORKS - INTRO

Development of wiring systems



Direct wiring



Bus systems

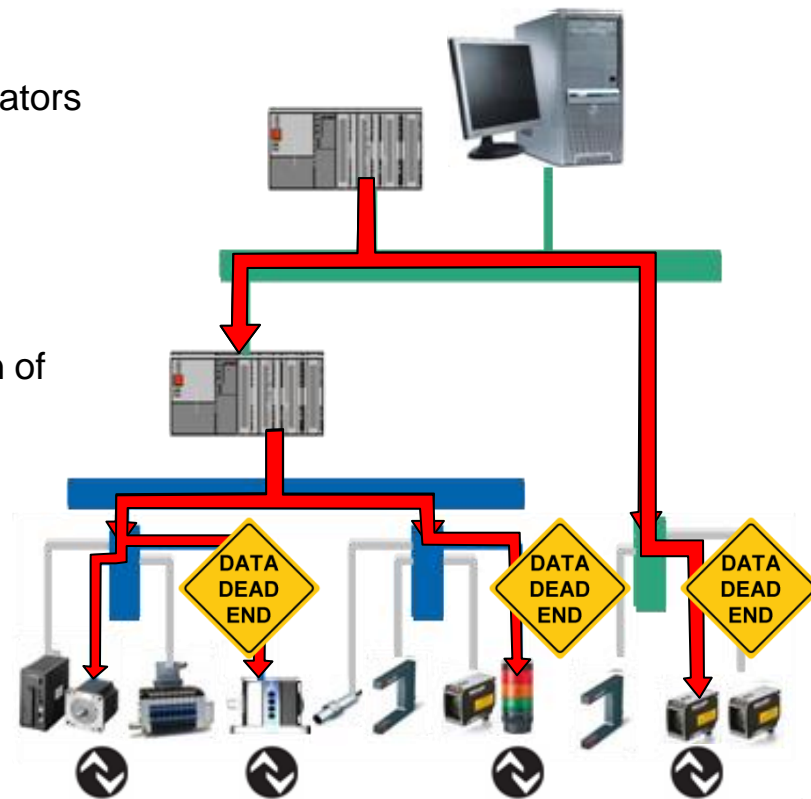
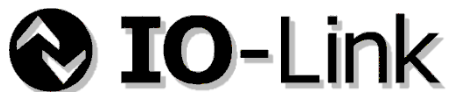


Distributed I/O

SENSOR NETWORKS - INTRO

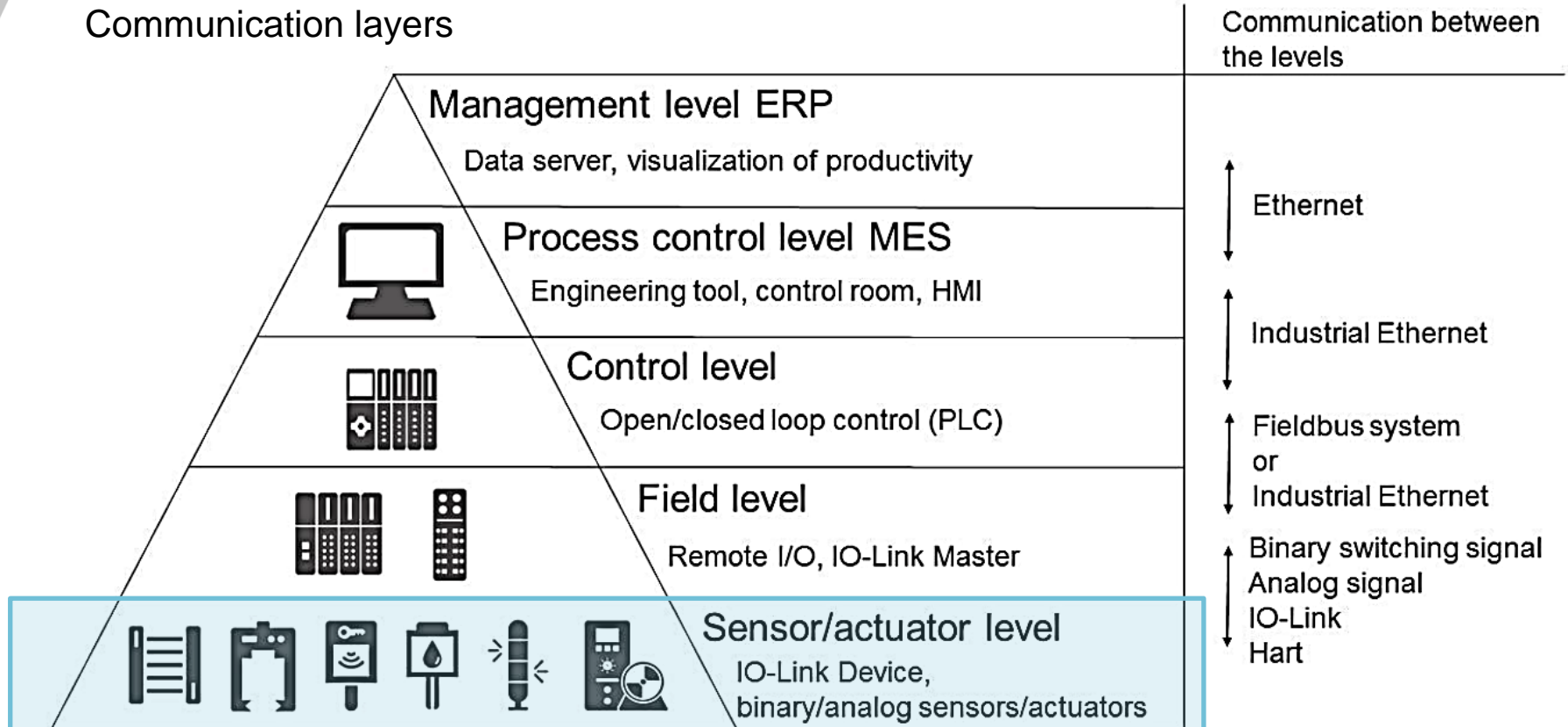
Distributed I/O

- Direct digital communication with sensors and actuators
- Digital, disturbance tolerant communication
- Access to the intelligence of sensors and actuators
- Easy up- and download of parameters
- Central, online access to the diagnostic information of field devices
- Uniform communication



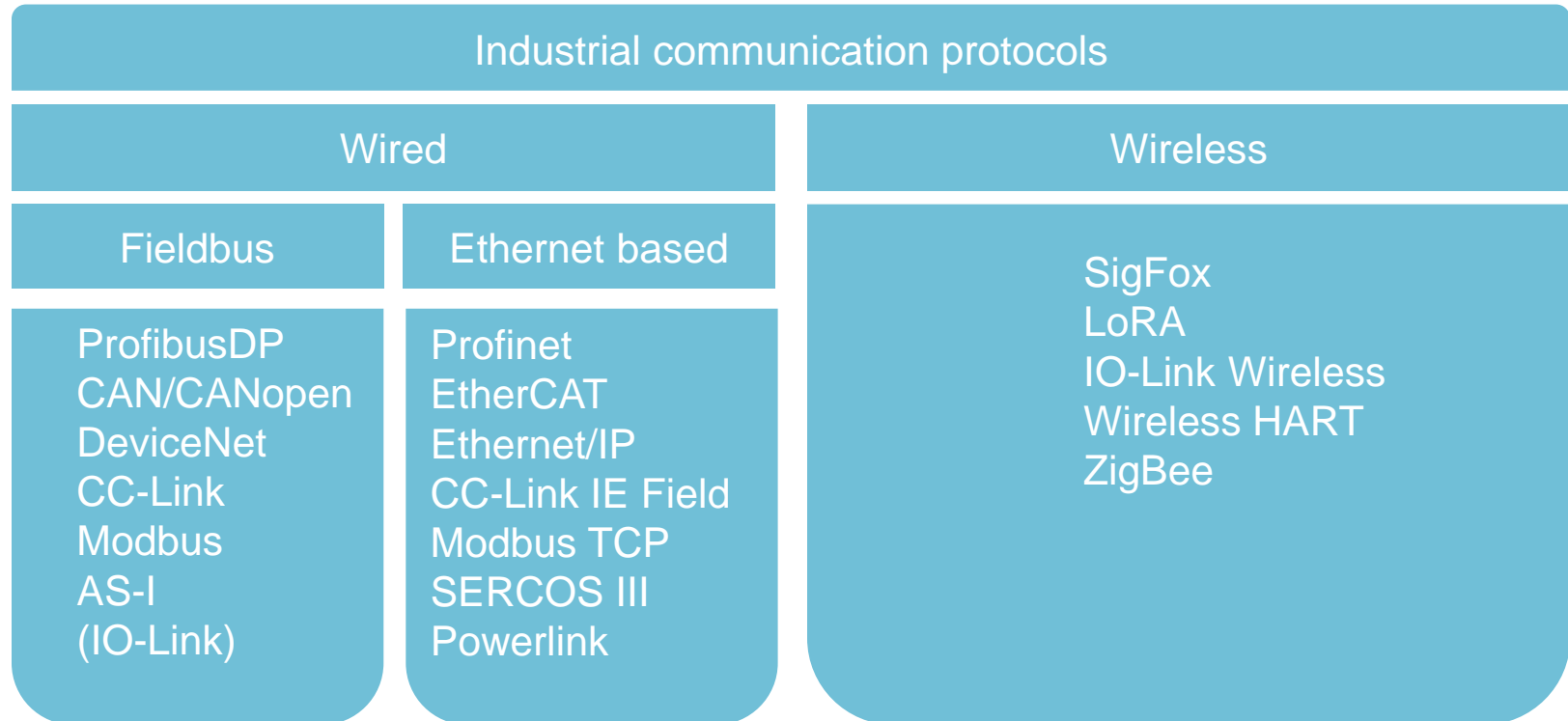
SENSOR NETWORKS - INTRO

Communication layers



SENSOR NETWORKS - INTRO

Industrial communication protocols



SENSOR NETWORKS - INTRO

Protocol

The term protocol comes from **Byzantine Greek**. "*protos*" means "first"; "*kolla*" means "one", from which the term "protocol" was formed, which is the **front sheet** glued to the papyrus rolls, on which the **roll's data** (official approval, date of creation, etc.) were written.

Since in the original sense it actually meant **order in the archive**, in this spirit it could be transferred to the field of high-ranking secular relations - in its classical form diplomacy - **indicating the order to be followed.**

Apart from its primary meaning (protocol = **meeting minutes**) in most languages, the concept of protocol is increasingly used in areas other than diplomacy in its second meaning.



M2M **communication** is everywhere



communication
 Kommunikation
 kommunikáció
 コミュニケーション
 comunicaci6n
 溝通
 комуникација
 ukuxhumana
 επικοινωνία

Source: <https://studyonline.ecu.edu.au/blog/securing-iot-unique-challenge-machine-machine-communication>

M2M communication in automation



Source: <https://studyonline.ecu.edu.au/blog/securing-iot-unique-challenge-machine-machine-communication>

Source: <https://www.dreamstime.com/automation-icon-robotic-arm-icon-simple-vector-icon-automation-icon-robotic-arm-icon-white-background-image142304714>

SENSOR NETWORKS - INTRO

The description of (industrial) communication protocols

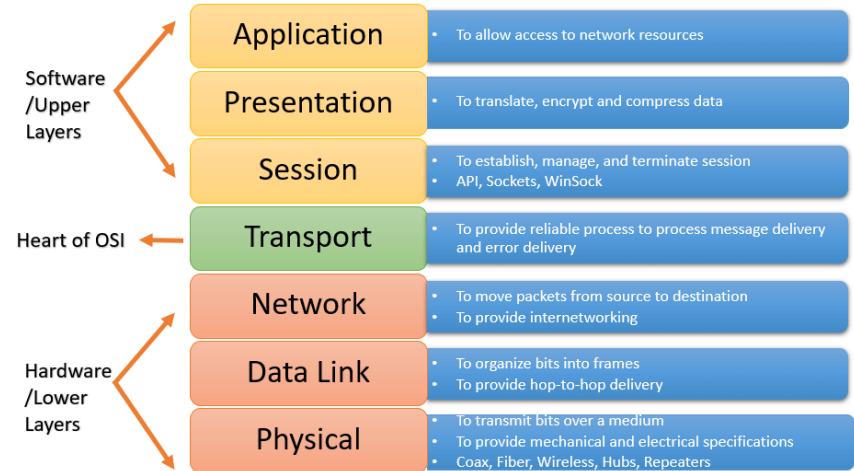
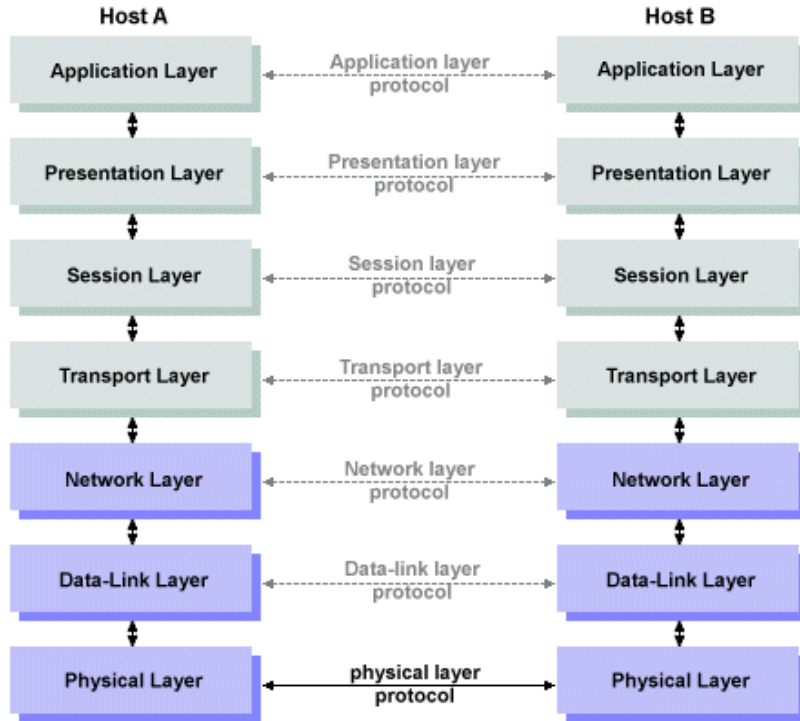
„Ogres are like onions.... *Onions have layers. Ogres have layers. We both have layers.*”



Communication protocols are like ogres and onions. **They have layers.**

SENSOR NETWORKS - INTRO

The description of (industrial) communication protocols



SENSOR NETWORKS - INTRO

Distributed I/O



service,
maintenance,
settings



PLC



Industrial Ethernet

Fieldbus

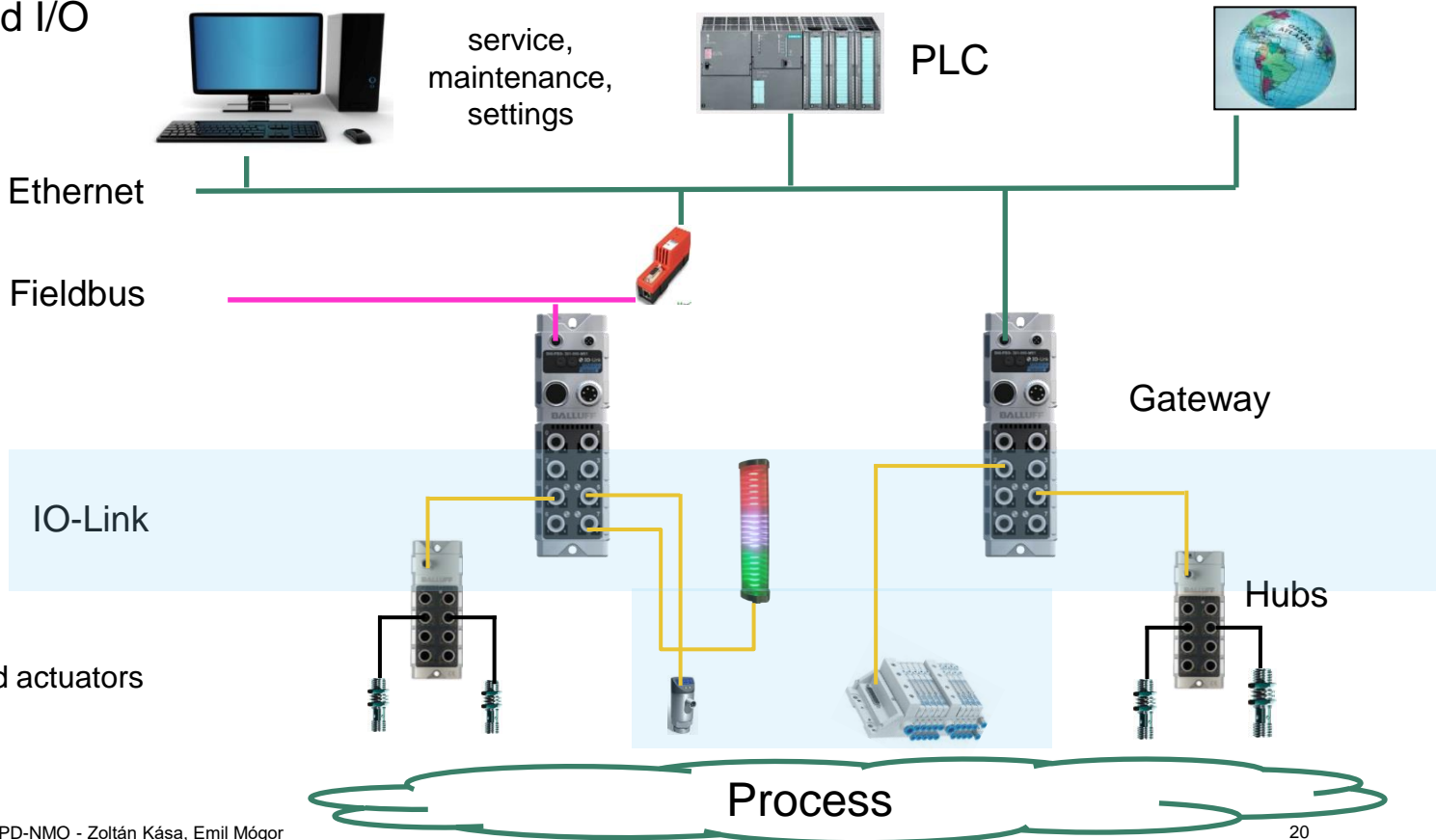
Gateway

IO-Link

Hubs

Sensors and actuators

Process



SHORT **LIVE DEMO**

with a PLC, Gateway and IO-Link Devices

Quiz Game

are these **protocols**?

CAN

CC-Link

ppt

UTP

https

FTP

Dress Code XML

PHP

UART

VEB

SPI

OLED

IP

C++

Gateway

Ethernet

LAN

Wi-Fi

Bluetooth

Profinet

JPG

WWW

PLC

QUIZ GAME

Protocols

IP https
Ethernet FTP
UTP
Wi-Fi UART
Bluetooth
Profinet CAN
CC-Link

Protocol
converter

Gateway

Something else

PLC XML
PHP ppt
VEB
Dress Code
UTP JPG LAN
SPI C++
WWW OLED

Please welcome on the stage...

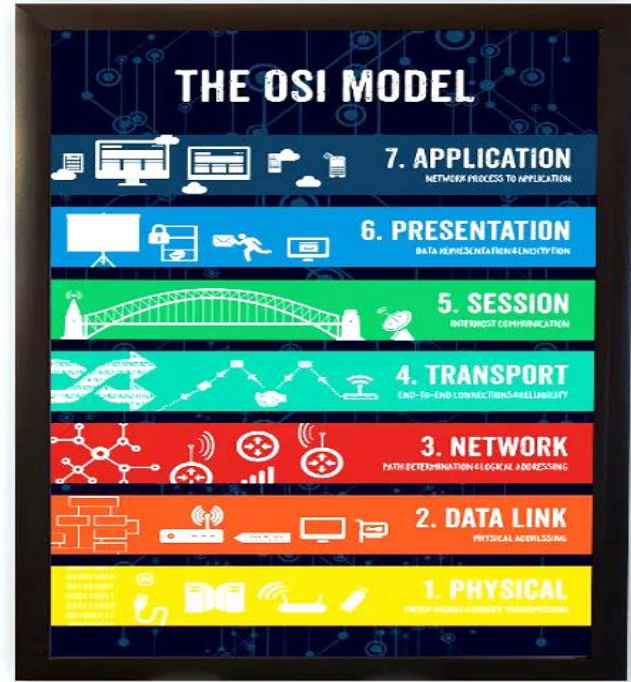


IO-Link

IO-Link is the first standardised IO technology worldwide IEC 61131-9(2013) for the **communication with sensors and also actuators.**

It is an open standard.

Simplification



Simplification



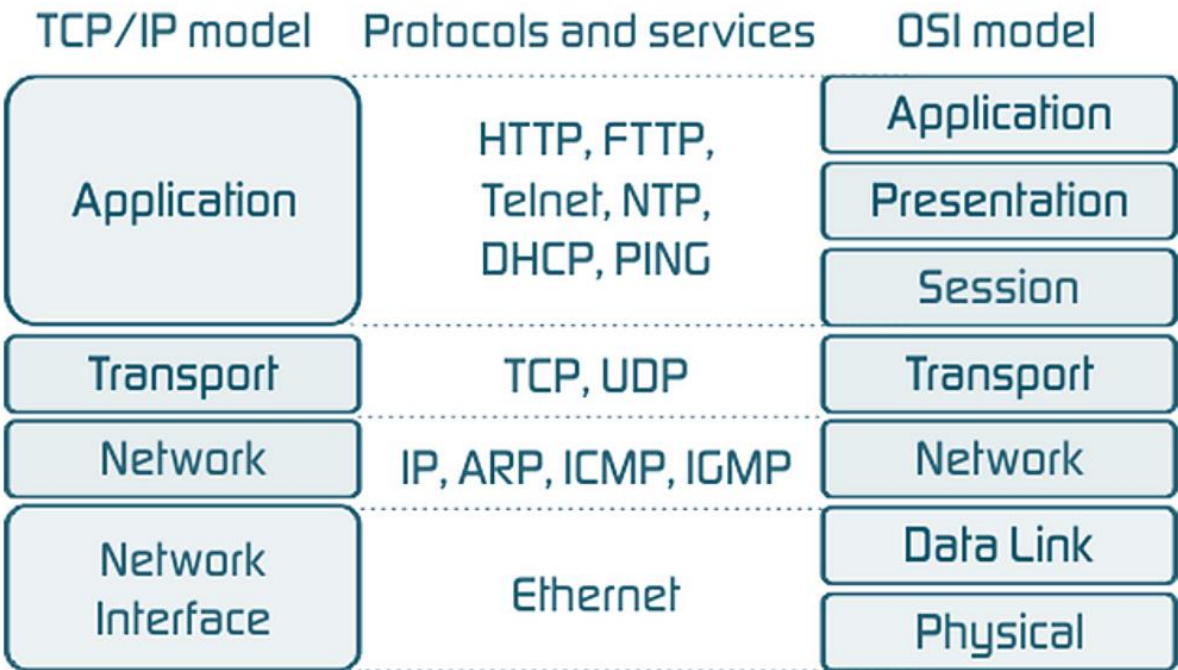
Simplification

IO-Link model

Application

Data Link

Physical



Layers

Three layers implemented from ISO/OSI reference model

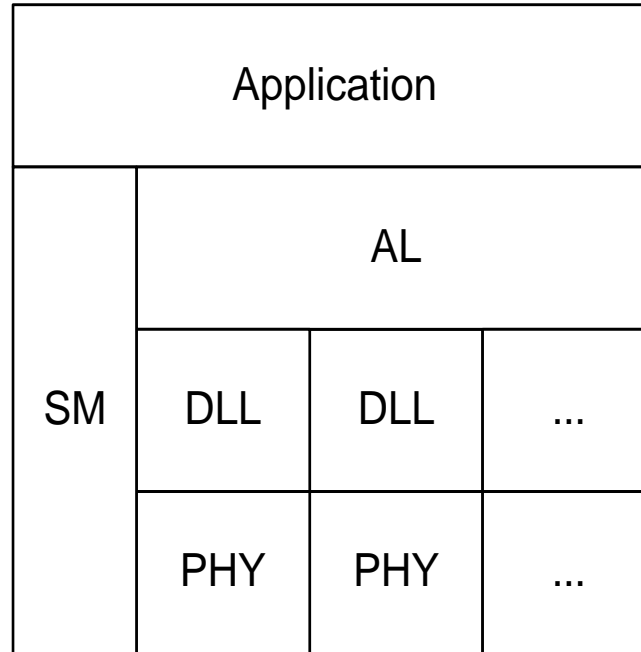
AL – Application layer

DLL – Data Link Layer

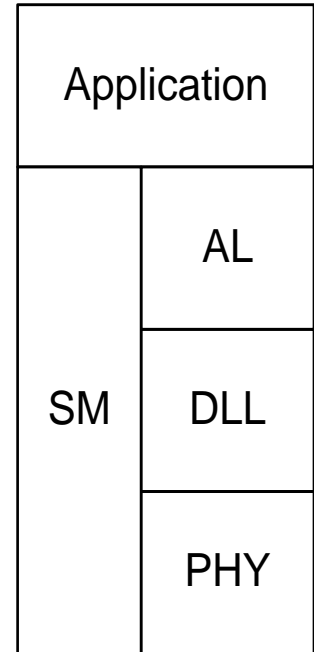
PHY – Physical Layer

SM – System Management

Master



Slave

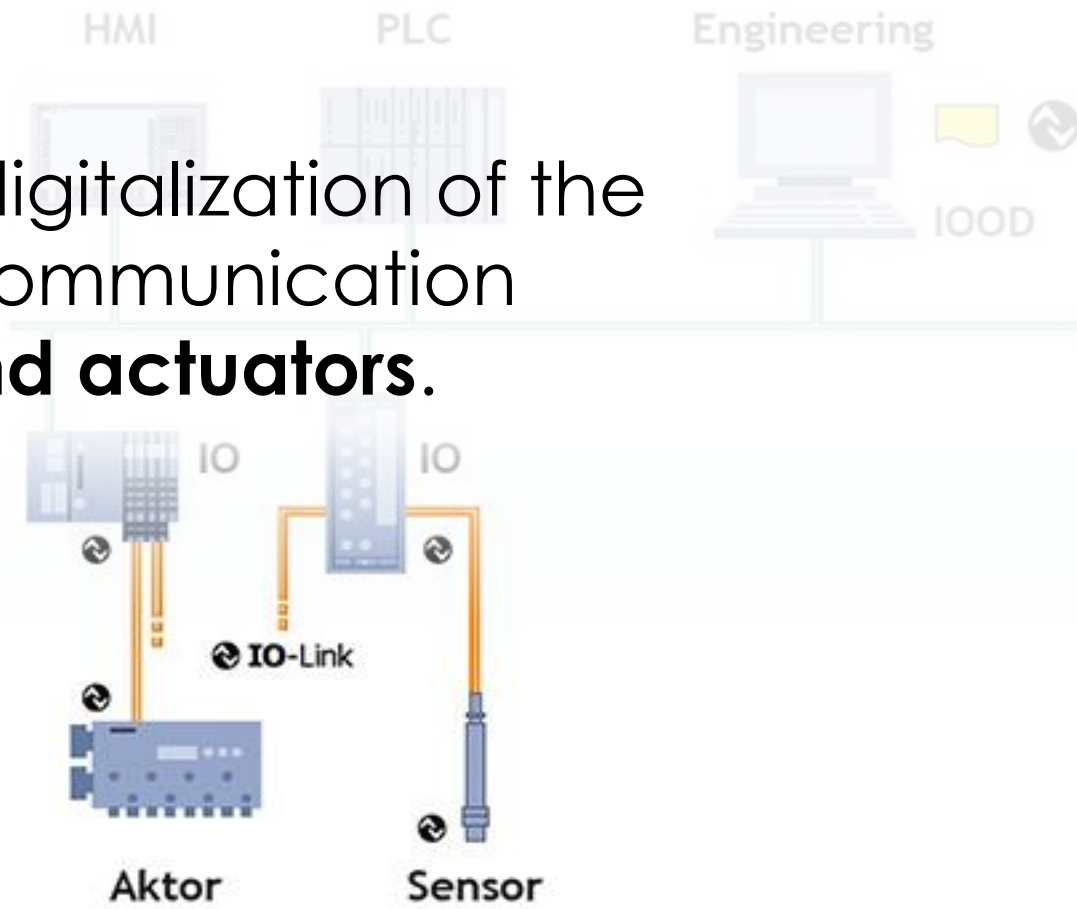


IO-Link medium (cable)

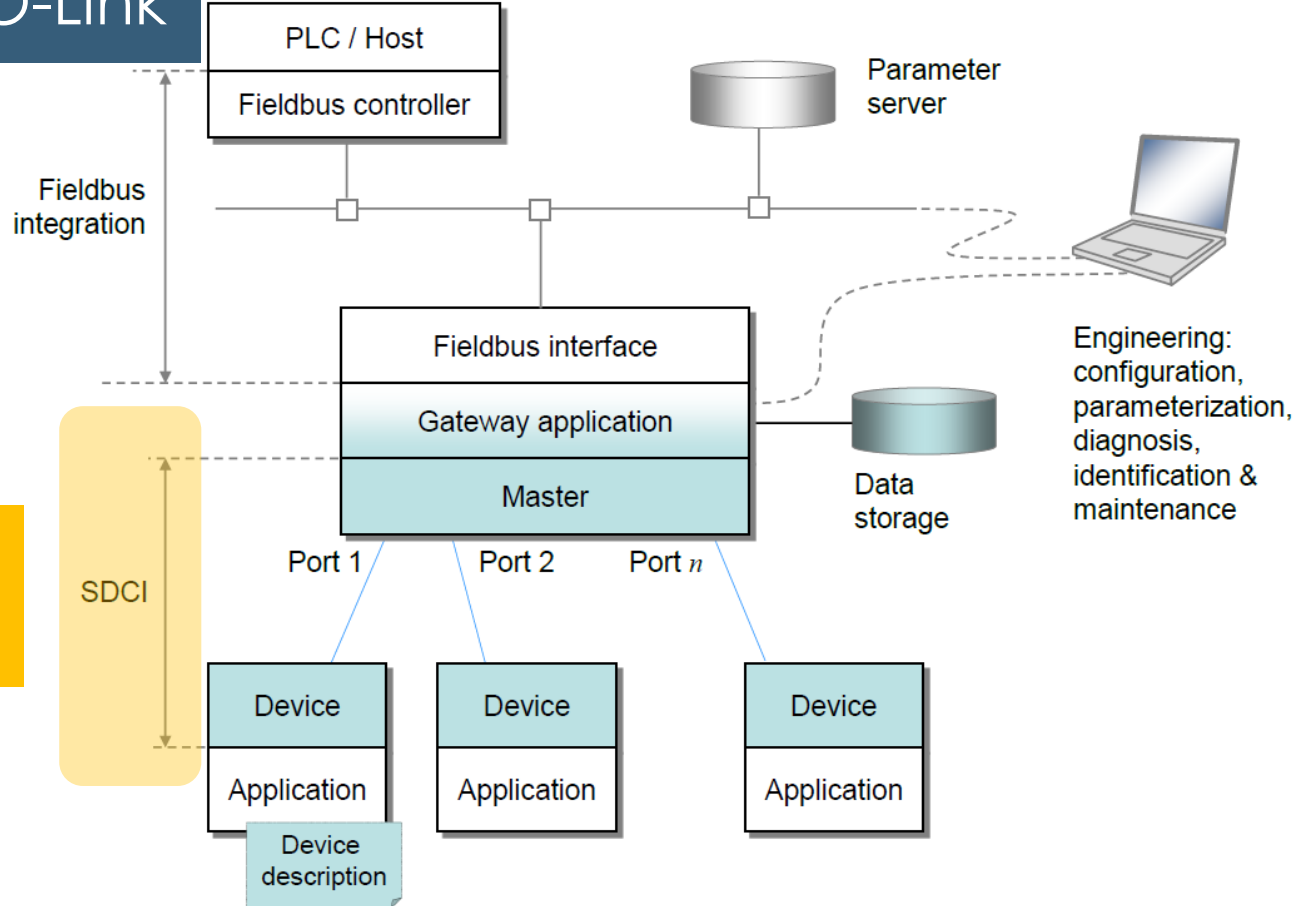
IO-Link

IO-Link provides for digitalization of the “last metre” of the communication link to the sensors and actuators.

IO-Link is the Industry’s USB




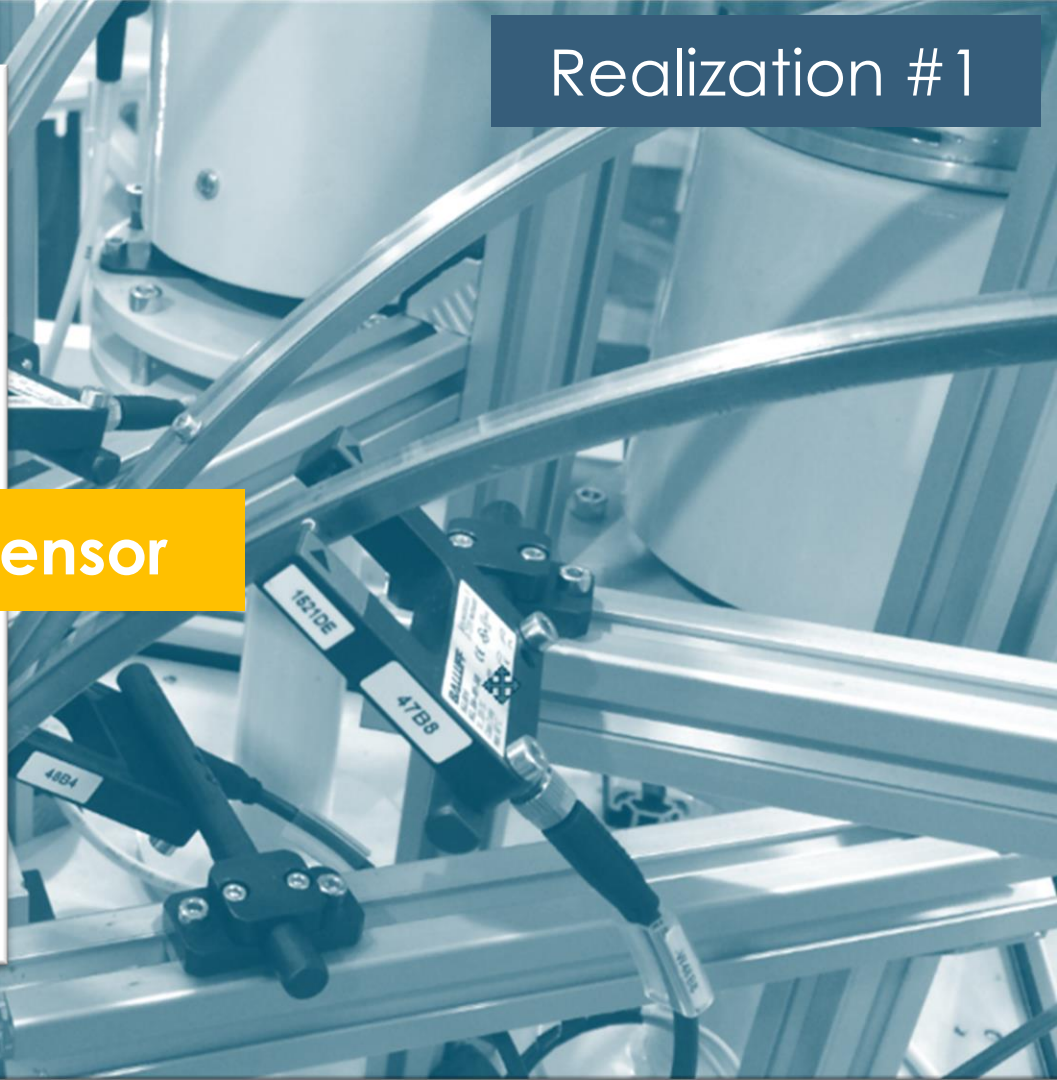
Placement of IO-Link



Protocol for the last meters


Opto-sensor

 IO-Link





Pressure sensor

 IO-Link



Realization #3



Gateway

 IO-Link



„I communicate, therefore I exist”



**Hey,
How are you?**

Thanks!



Main characteristics

Point-point access

For sensors and actuators

Cyclic communication

Fixed Baudrates
(4.8, 38.4, 230.4 kbps)

Half-duplex communication

Diagnostics

IO-Link Master

Field-bus independent
(pl: CC-Link, Profinet, Ethernet...)

IO-Link Device

Other aspects

IO-Link Master



IO-Link Device

Bővíthetőség

Easy integration

Maintenanceability

Low installation cost

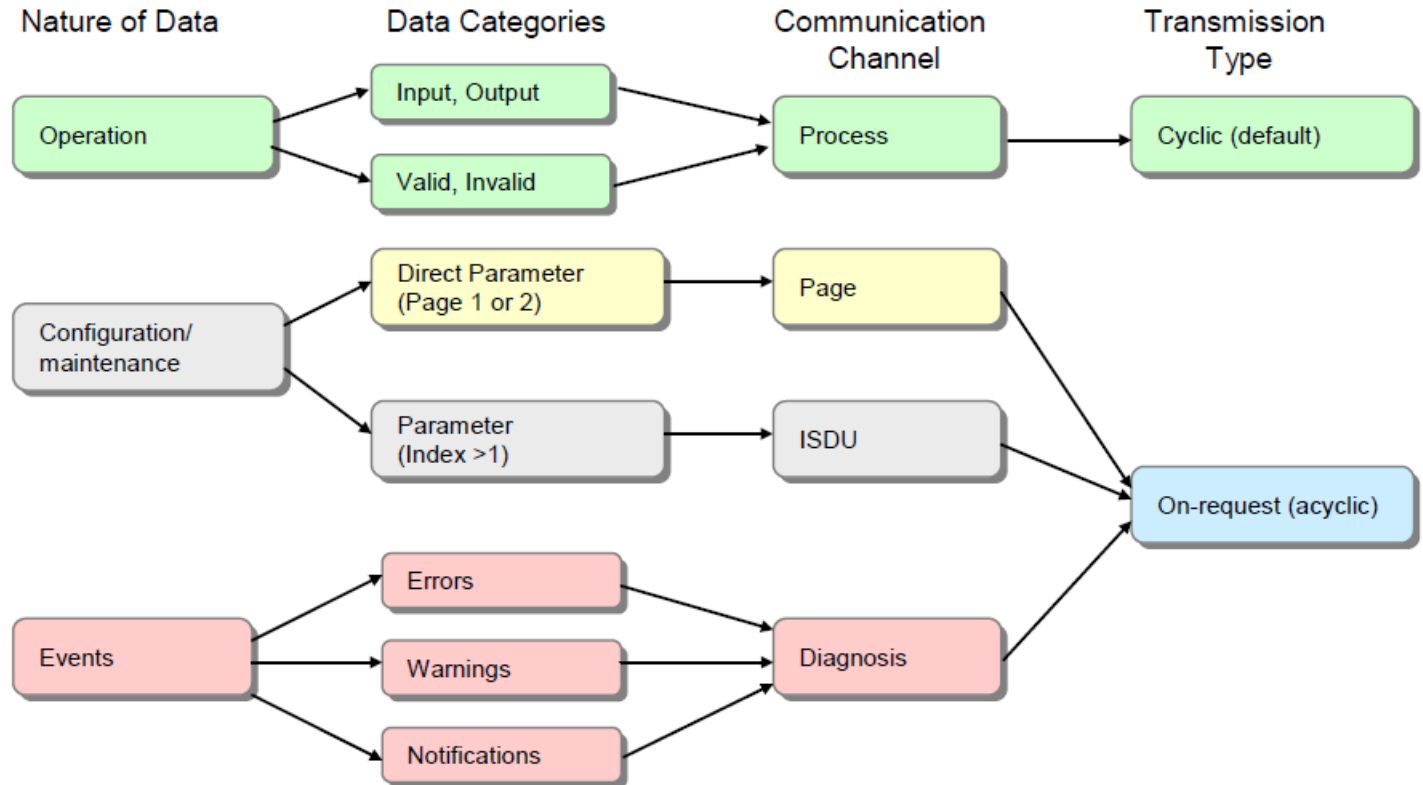
Easy to use

Compatibilty

No special cables required

24 Volt compatible

Logical channels





Three levels of the communication

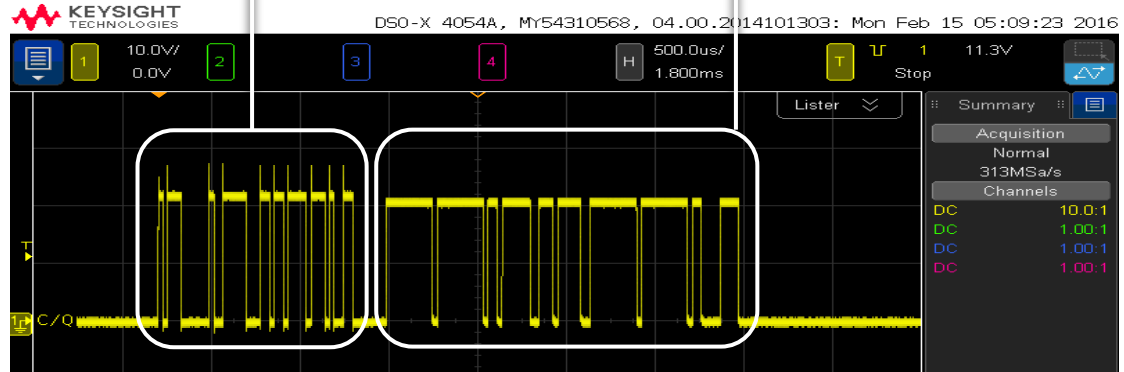
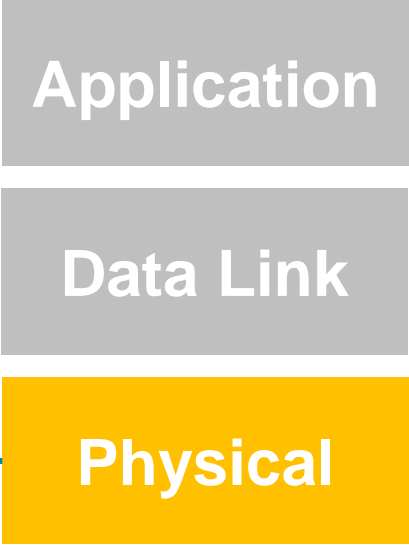


Application

Data Link

Physical

Three levels of the communication



UART characters

1110001 10000011 00010010 (0/24 Volt)

Three levels of the communication

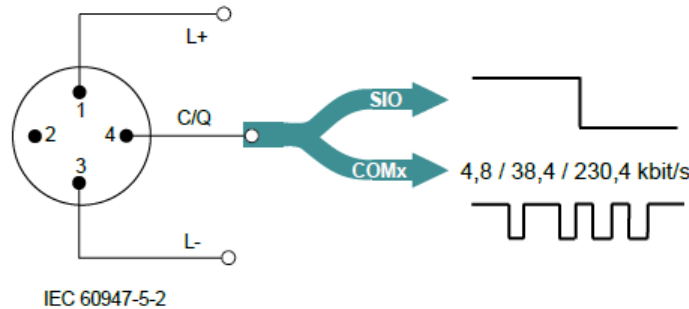
Application

Data Link

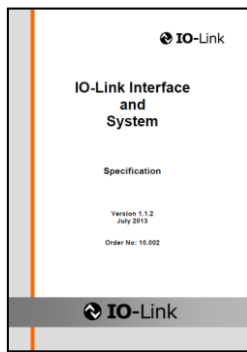
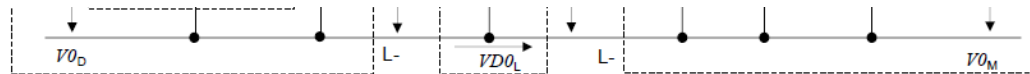
Physical

Physical line driver

Compatible
 With 24 Volt digital I/O devices (IEC 61131-2)



Pin	Signal	Definition	Standard
1	L+	24 V	IEC 61131-2
2	I/Q	Not connected, DI, or DO	IEC 61131-2
3	L-	0 V	IEC 61131-2
4	Q	"Switching signal" DI (SIO)	IEC 61131-2
	C	"Coded switching" (COM1, COM2, COM3)	IEC 61131-9





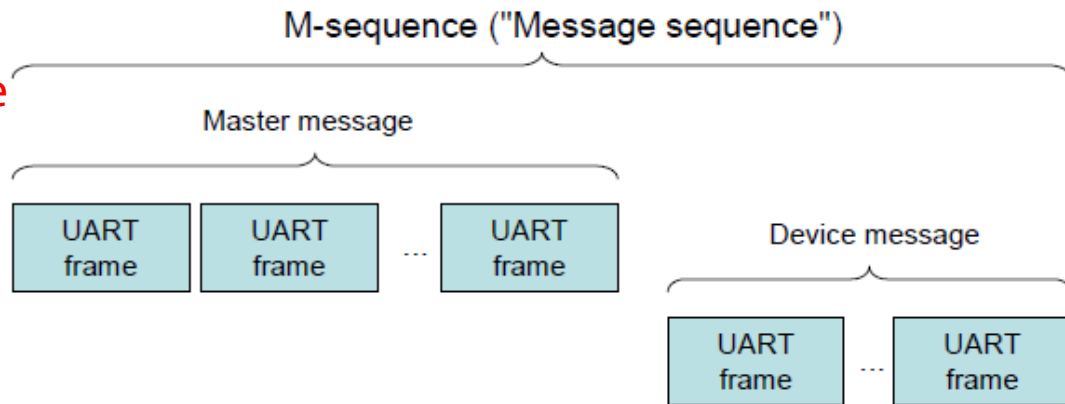
Telegrams

Sent by the Master:

- MC: M-sequence control byte
- CKT: CHECK and TYPE byte
- PD: Output Process Data
- OD: On-request adat

Sent by the Device:

- OD: On-request data
- PD: Input Process Data
- CKS: Checksgup and Status

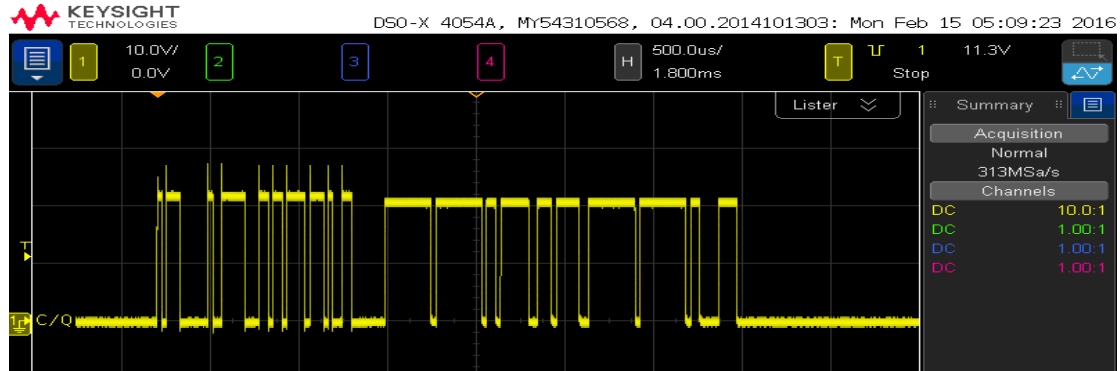


Telegram

Application

Data Link

Physical



Scope measurement

- One UART
- One Frame
- Cyclic Messaging

Three levels of the communication

Hogyan?

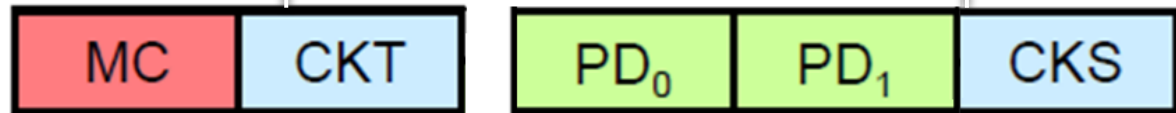
IO-Link Master

IO-Link Device

Application

Data Link

Physical



Data: 16,4

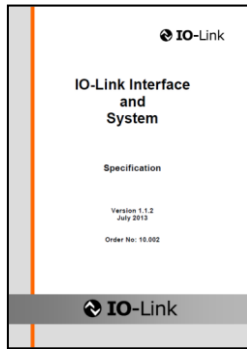
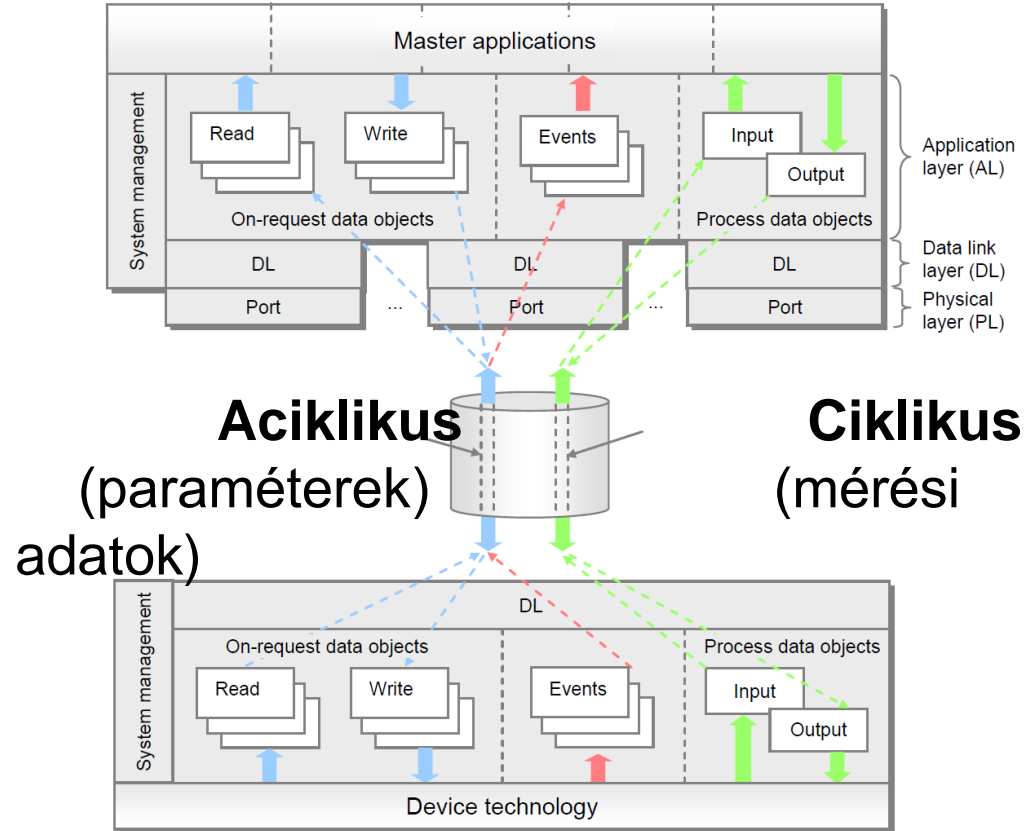
MC: M-sequence control bájít
CKT: CHECK/TYPE bájít
OD: On-request adat
CKS: Checksum, státusz

Three levels of the communication

Application

Data Link

Physical



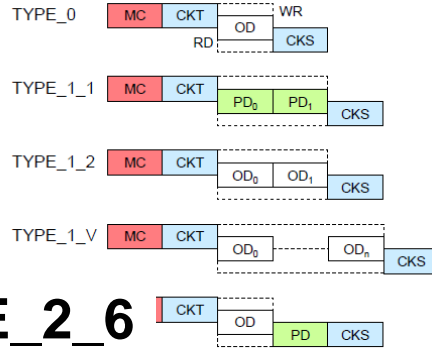


Three levels of the communication

Application

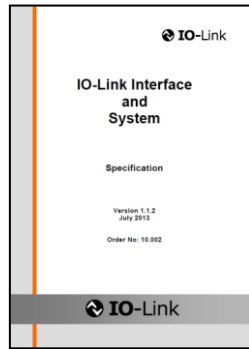
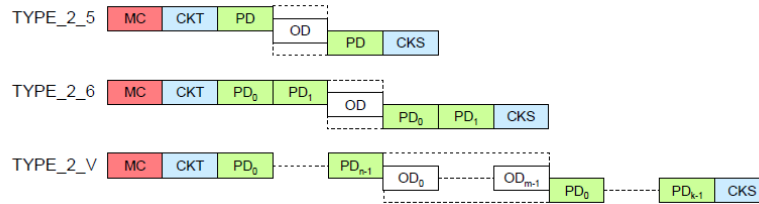
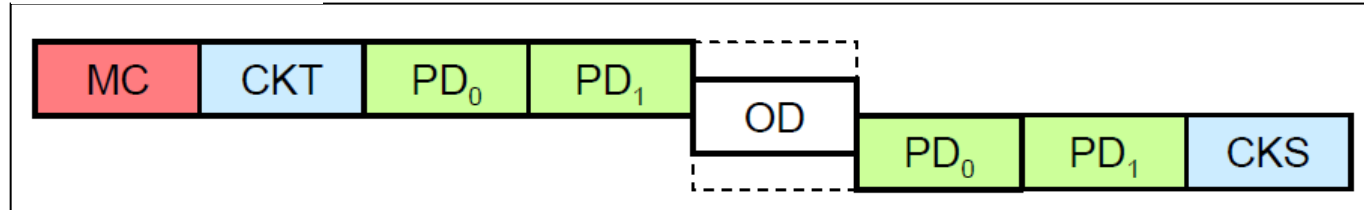
Data Link

Physical



TYPE_2_6

Frame/Message Types





Three levels of the communication

Application

Data Link

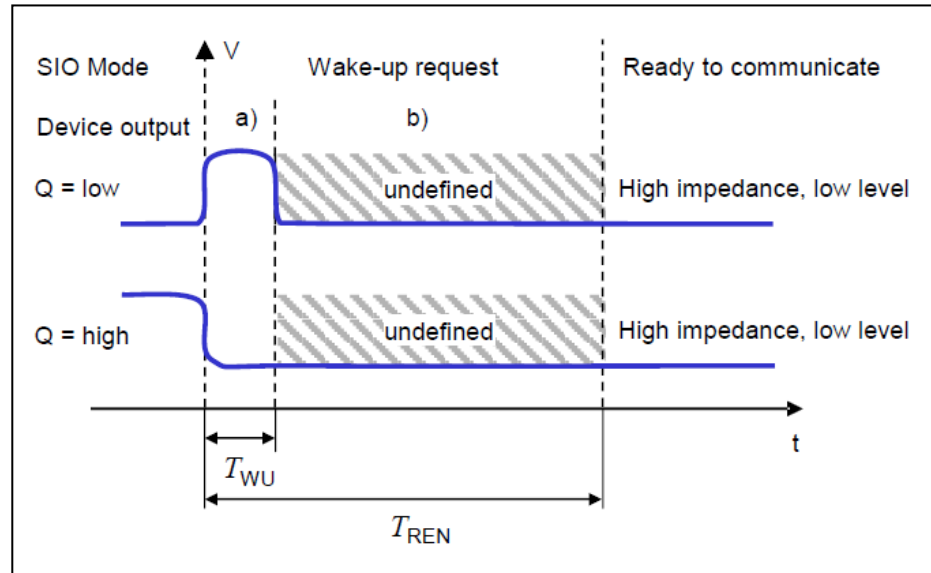
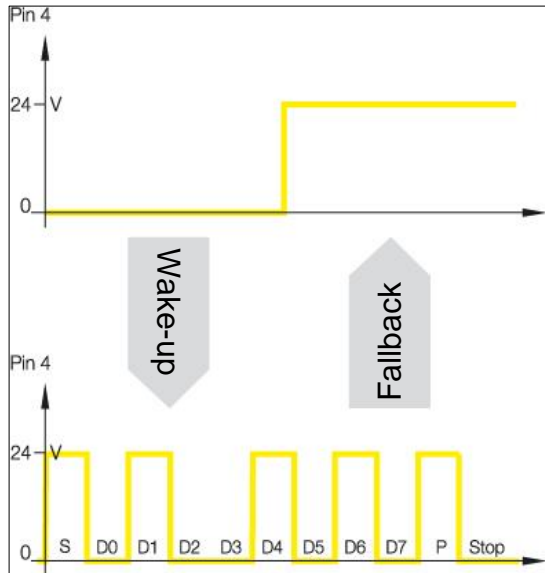
Physical

IO-Link States

- Wake-up / Fallback
- Startup
- Preoperate
- Operate

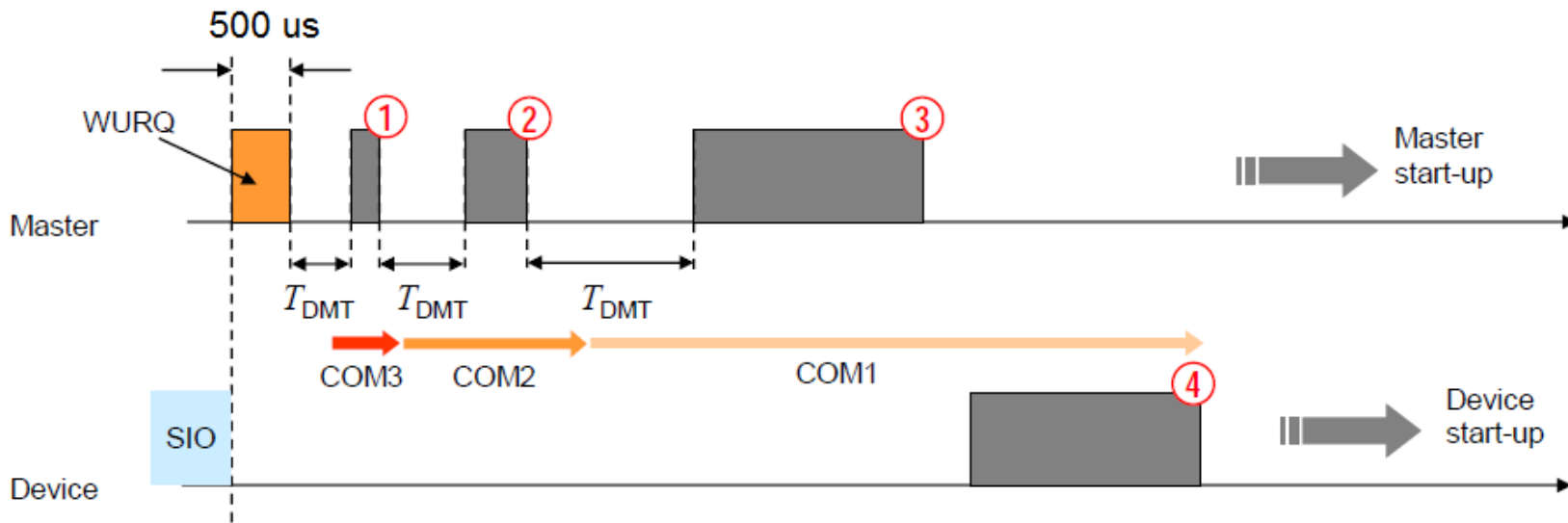
Establish the communication

SIO versus IO-Link



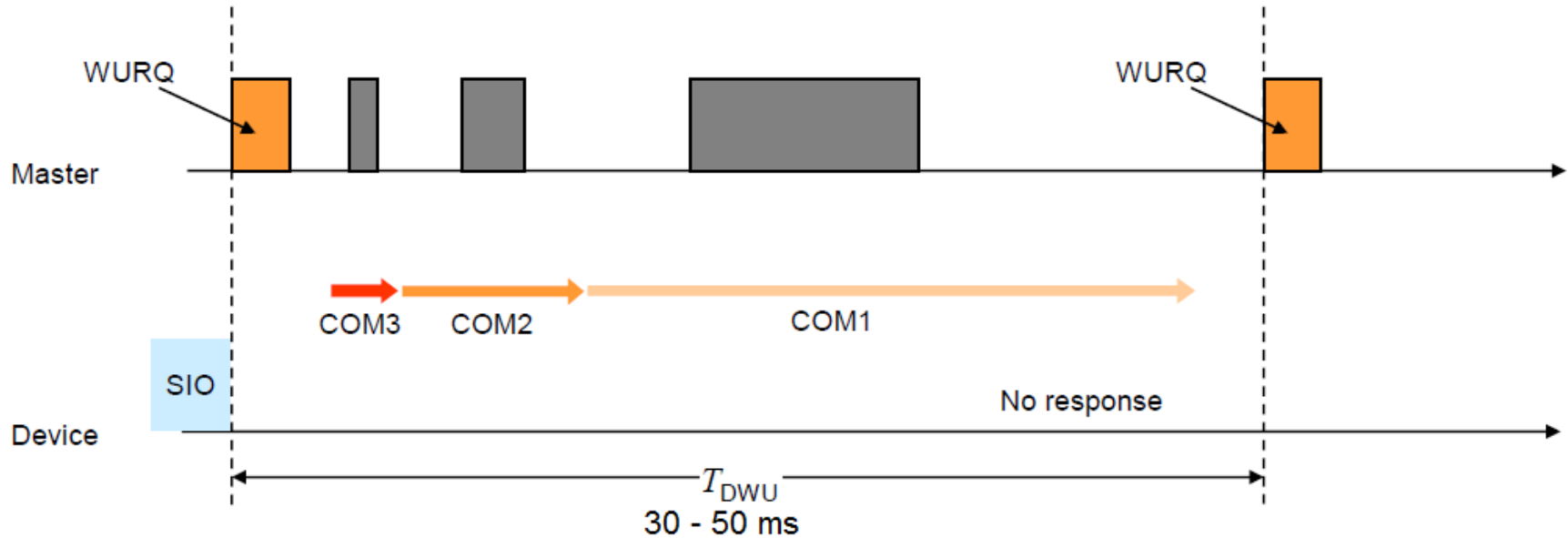
Establish the communication

Wake-up



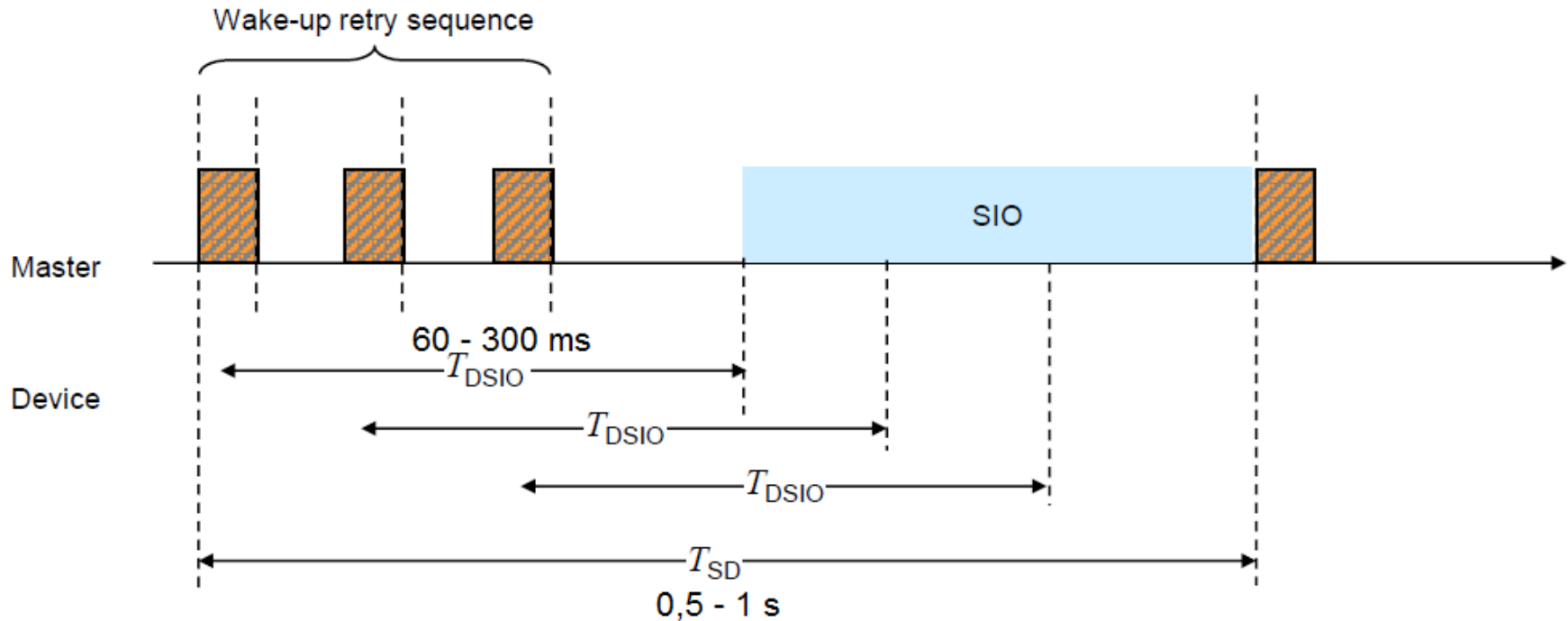
Establish the communication

Wake-up



Establish the communication

Wake-up



Establish the communication

Fallback

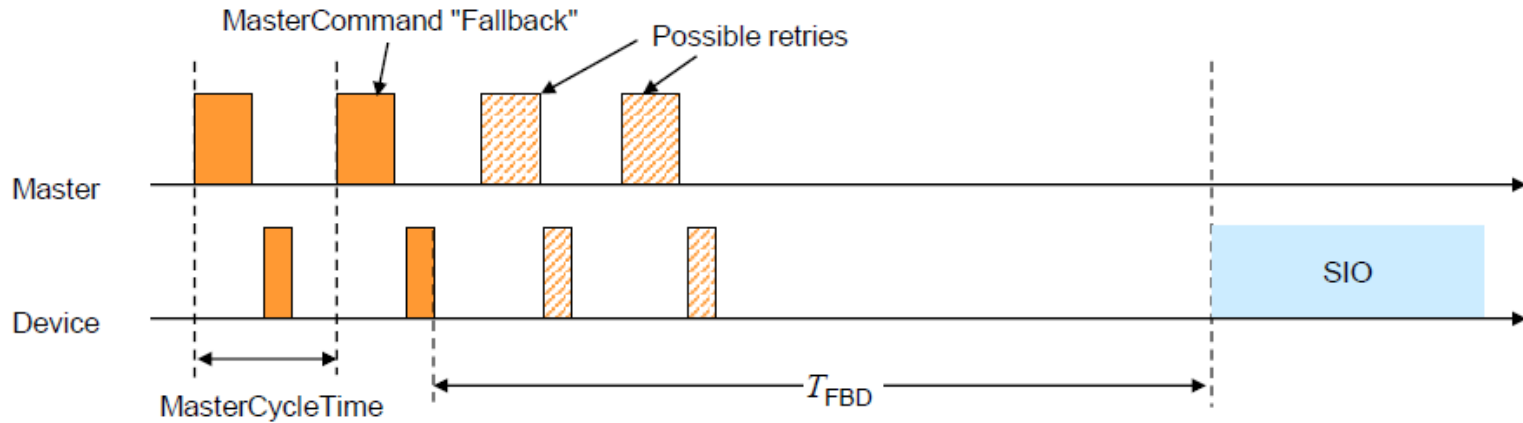
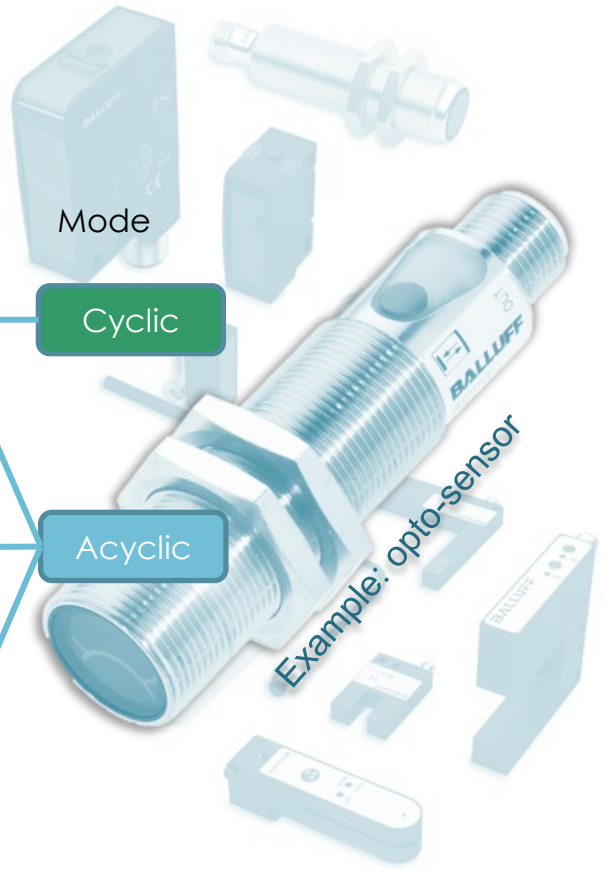


Figure 32 – Fallback procedure

Three levels of the communication

- Application
- Data Link**
- Physical

Data	Channel	Mode
Distance = 14.7 mm	PD	Cyclic
Cycletime (data exchange rate) = 6 ms	DPP	Acyclic
Threshold = 10.0 mm	ISDU	
Dirty glasses!	Diagnosis	



Three levels of the communication

Data + Description = Information

Application

16,4 means
Object distance = 16,4 mm

Data Link

Description

Data

Physical

*Milyen jellemzőt mér a szenzor?
Mi a mértékegység?
Milyen paramétereit vannak?
Milyen diagnosztikával rendelkezik?
Milyen funkciókat tud?*

IODD

IO Device Description



PLC



Sensor

Three levels of the communication

Application

Data Link

Physical

IODD
IO Device
Description



Service
Maintenance
Parameterization

PLC

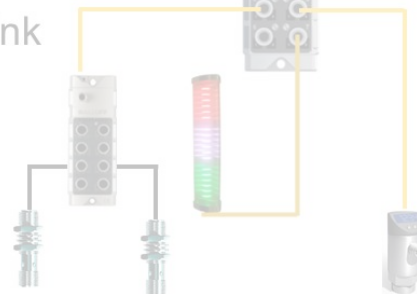


Terepbusz



IO-Link Master

IO-Link



IO-Link Device

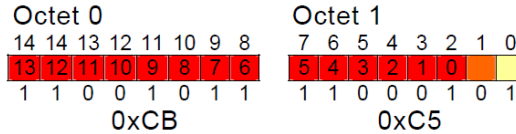
Three levels of the communication

Application

Data Link

Physical

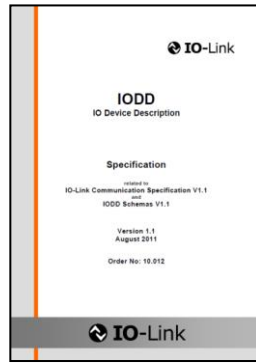
RecordItem	Subindex	Datatype	bitLength	bitOffset	Value
1	1	UIntegerT	14	2	0x32F1
2	2	BooleanT	-	1	false
3	3	BooleanT	-	0	true



IODD
IO Device
Description

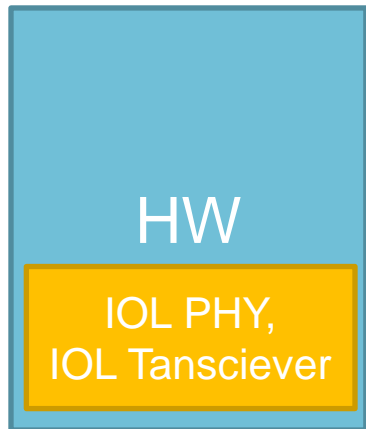
Formal description
(data type, name, length)

```
<Datatype xsi:type="RecordT" bitLength="16">  
  <Name textId="TI_ProcessData"/>  
  <RecordItem subindex="1" bitOffset="2">  
    <SimpleDatatype xsi:type="UIntegerT" bitLength="14"/>  
    <Name textId="TI_AnalogValue"/>  
  </RecordItem>  
  <RecordItem subindex="2" bitOffset="1">  
    <SimpleDatatype xsi:type="BooleanT"/>  
    <Name textId="TI_Signal2"/>  
  </RecordItem>
```

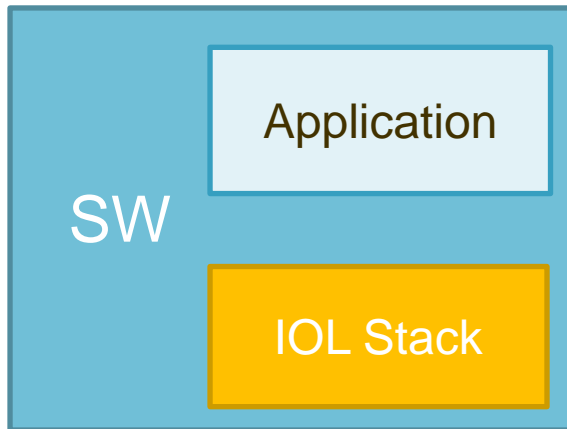


Schematic view of an IO-Link Device

What is in the box?



by HW supplier



by SW developers or
from IO-Link Competence Center



The hardware

Source: <https://datasheets.maximintegrated.com/en/ds/MAX14824.pdf>

HW

IOL PHY,
IOL Transceiver

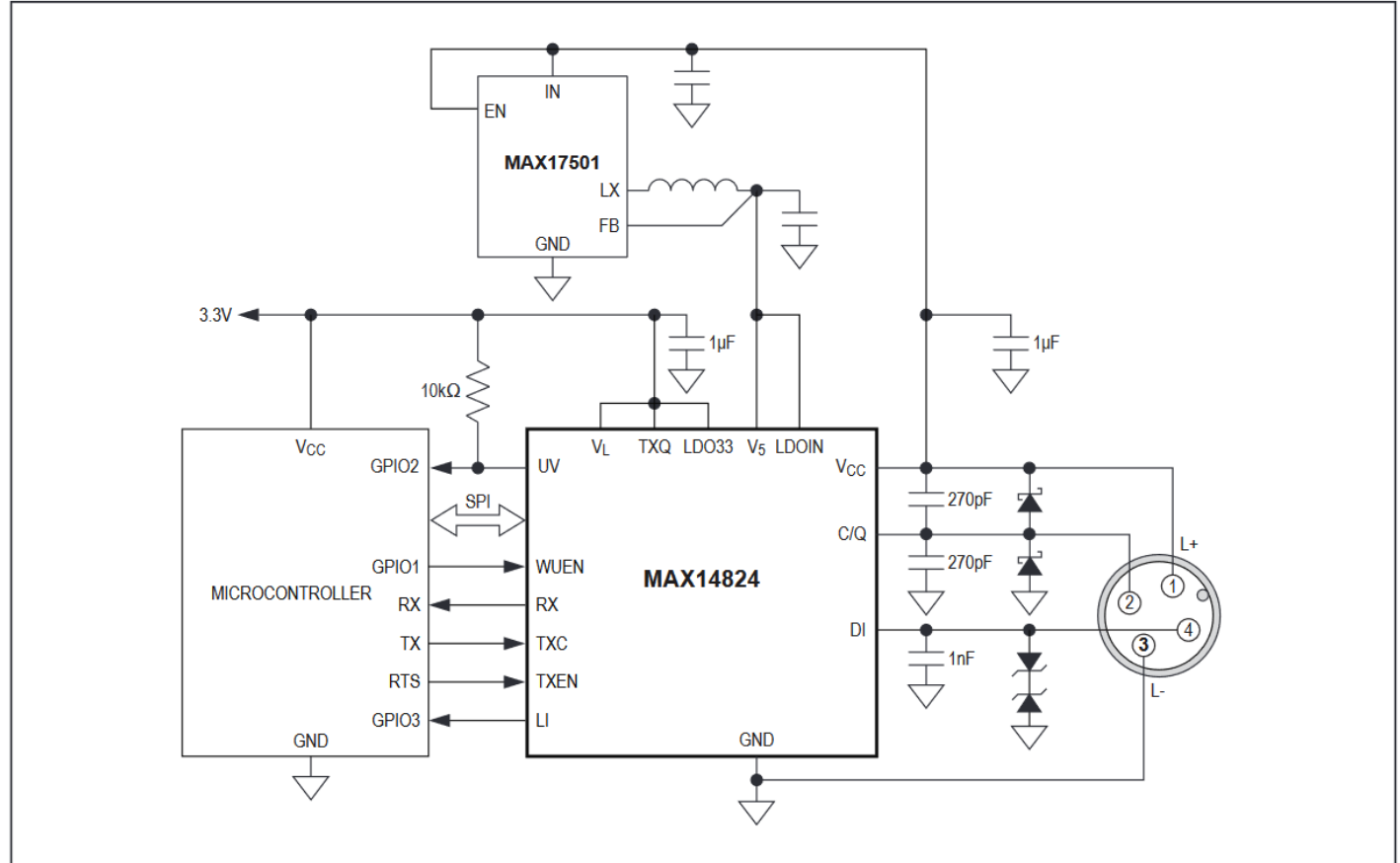
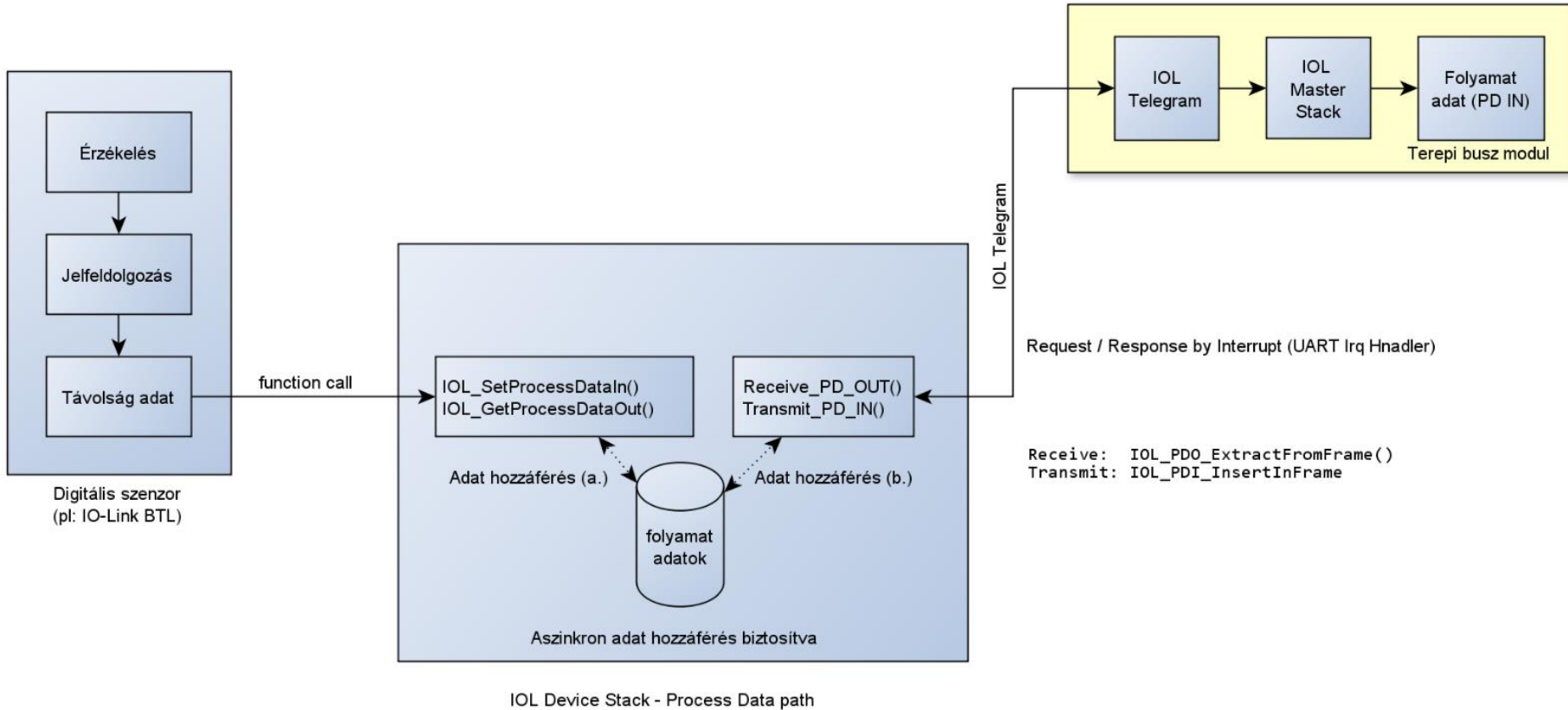


Figure 12. Use an External Supply to Power the MAX14824

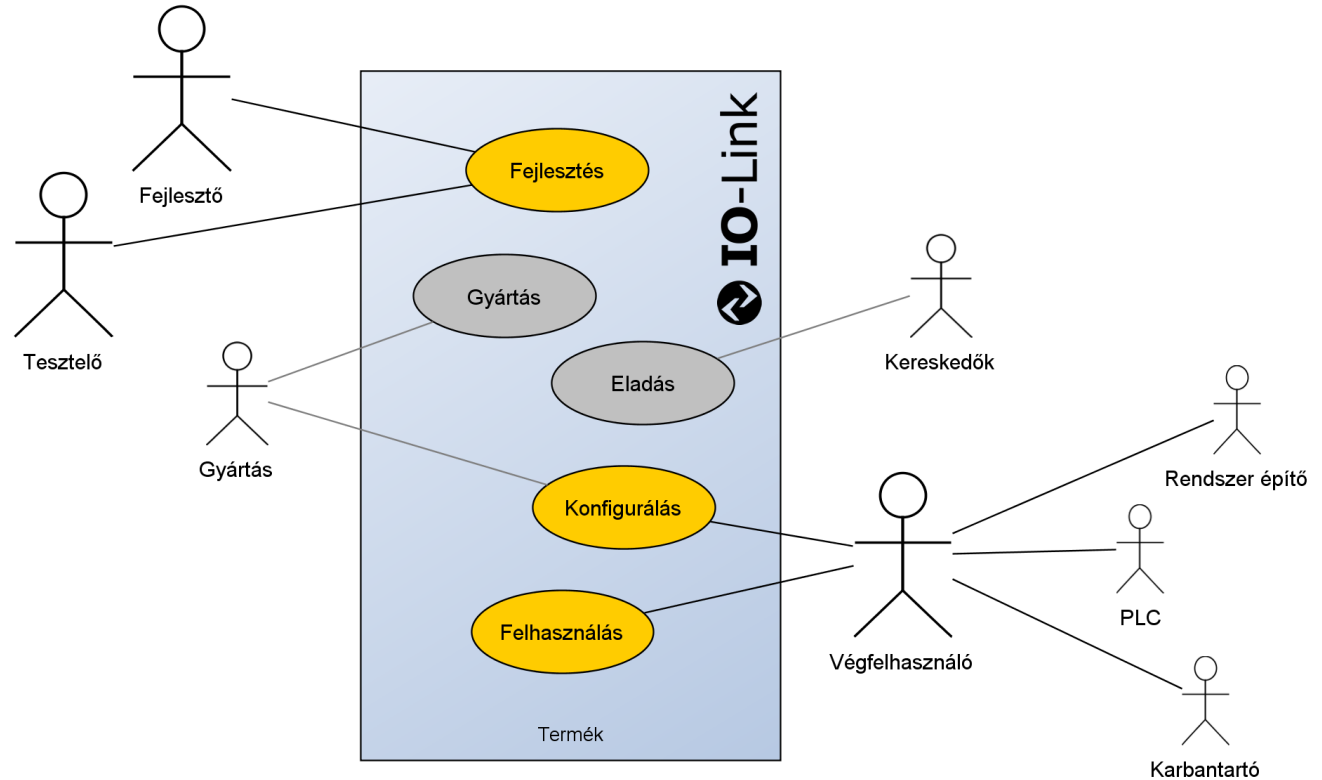
The software

firmware



IO-Link (device) Use Cases

Users of the protocol



The image shows the interior of an EMC test chamber. The walls are covered with white, cross-shaped electromagnetic absorbers. A red metal frame is suspended in the center, holding a white device. A blue coiled cable is connected to the device. In the background, a wooden table holds various electronic equipment and cables. The floor is dark and reflective.

Behind the scene

EMC